

Computer Graphics

Part I

entropia/CCC Karlsruhe

Two Parts

today:

- ▶ Color Perception
- ▶ Pixels
- ▶ Fractals
- ▶ Geometry and Material
- ▶ Rendering

Two Parts

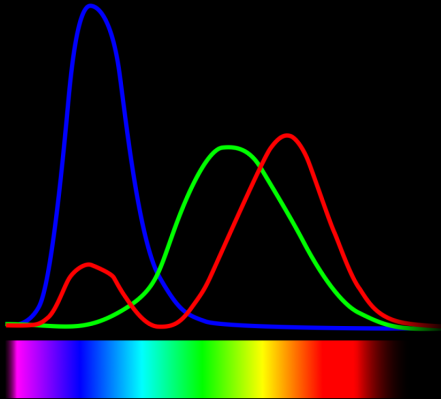
next time:

- ▶ Realtime Rendering
- ▶ hardware
- ▶ wicked shit
- ▶ demos

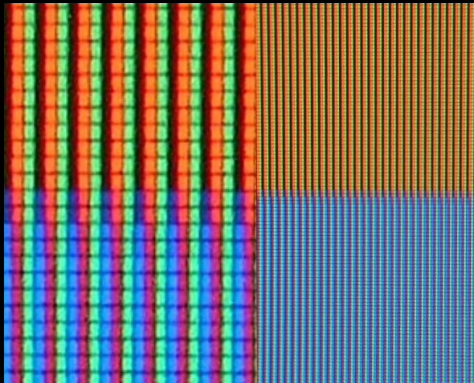
Spectrum



Color Perception



RGB



RGB



Traditional Color Formats

- ▶ $5+6+5$ bits (RGB) = 16bit
(“HighColor”)
- ▶ $3*8$ bits (RGB) = 24bit
(“TrueColor”)
- ▶ $4*8$ bits (RGBA) = 32bit

Dynamic Range

defined as

$$\blacktriangleright r = \frac{\max}{\min}$$

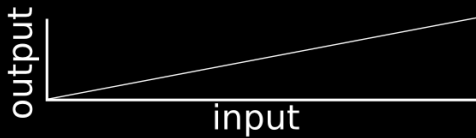
Dynamic Range

- ▶ human eye: 1,000,000
- ▶ computer displays: 1,000
- ▶ 24bit colors, per channel: 255

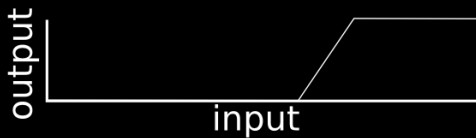
Tone Mapping

Reduce Dynamic Range while
preserving good looks

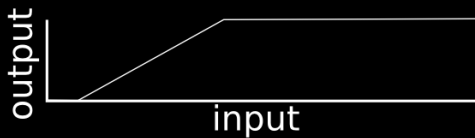
Tone Mapping



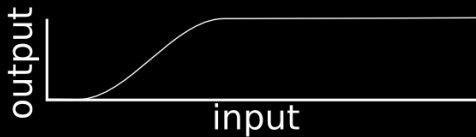
Tone Mapping



Tone Mapping



Tone Mapping



HDR Imaging

In classic Photography

- ▶ Tone Mapping by aperture/exposure
- ▶ no intelligent/custom Tone Mapping is possible

HDR Imaging

steps:

- ▶ acquire data from multiple LDR photographs
- ▶ generate a single HDR image
- ▶ Tone Map this image

HDR Imaging



HDR Imaging



HDR Rendering

- ▶ use HDR colors throughout the rendering process
- ▶ last step: Tone Map the rendered image

requires hardware support for 16bit floating-point textures

HDR Rendering

With HDR Rendering



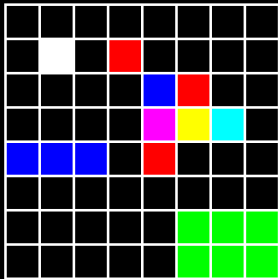
Without HDR Rendering



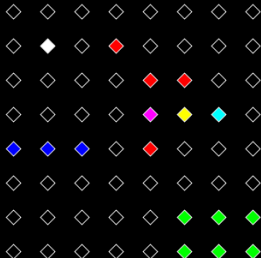
Pixels

pixel = “picture element”

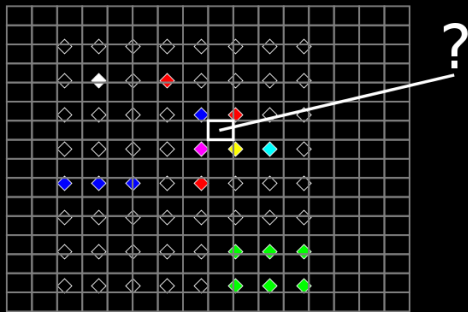
Pixels



Pixels



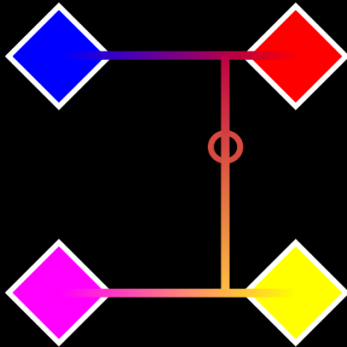
Resampling



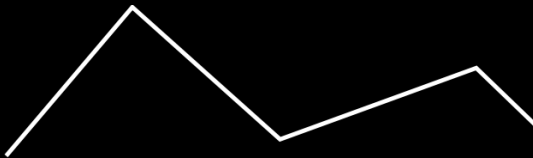
Sampling



Bilinear Filtering



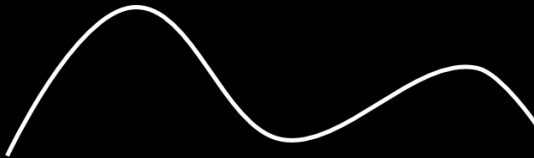
Linear Interpolation



Nearest Neighbour



Smooth Interpolation



Various Techniques

- ▶ Nearest Neighbour

- ▶ Linear

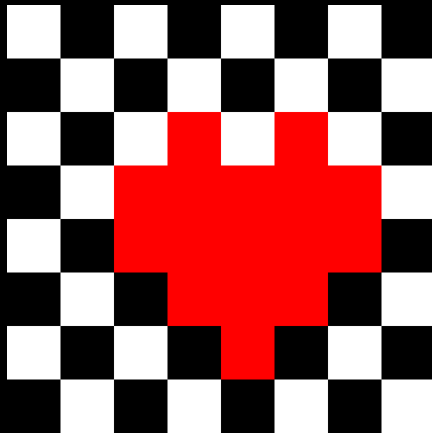
- ▶ Cubic: stitch many

$$f(x) = ax^3 + bx^2 + cx + d$$

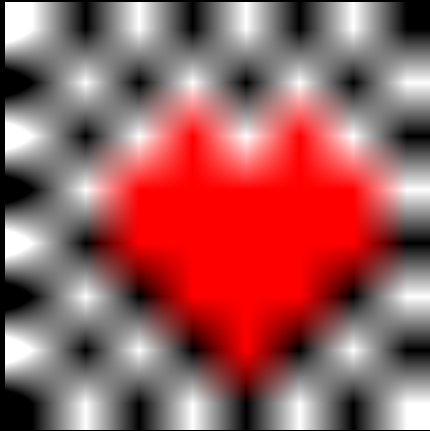
together

- ▶ Optimal: *sinc* Filter

Nearest Neighbour



Linear Interpolation



Cubic Interpolation



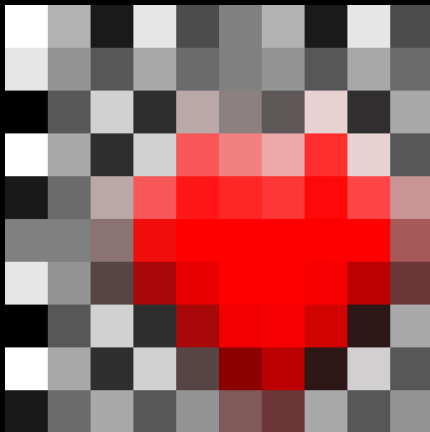
Signal Processing

Treat color information as a signal:

- ▶ pixel distance = sampling rate
- ▶ use Highpass/Lowpass Filters to access frequencies

→ JPG etc

Scaling small amounts



Downsampling

- ▶ must use more than four pixels
- ▶ perform a Lowpass Filter
- ▶ often ignored

Nearest Neighbour



Linear filtering



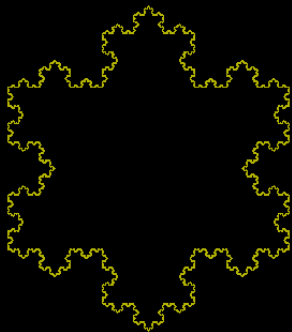
In Practice

- ▶ Nearest Neighbour: crappy software (browsers, pdf viewers)
- ▶ Bilinear: Graphics Hardware
- ▶ Bicubic etc.: Image Processing

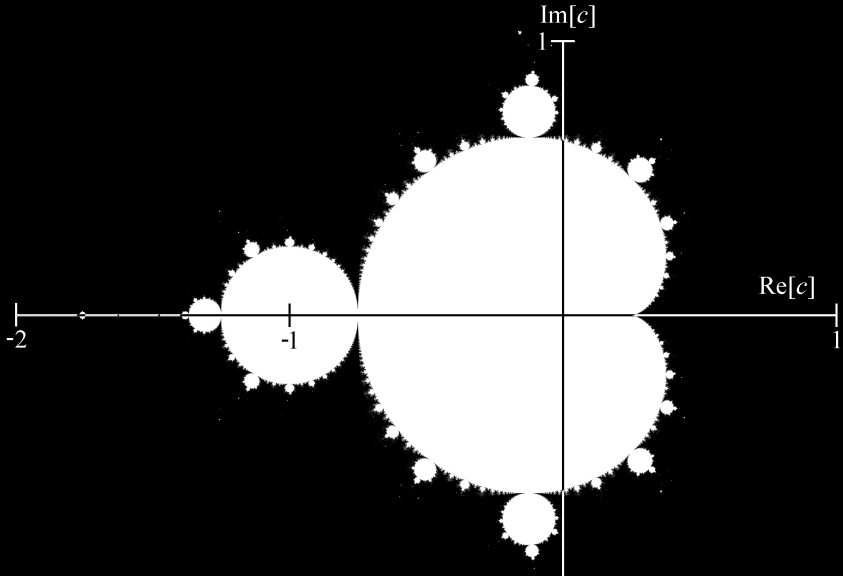
Fractals



etc.



Mandelbrot Set



omg complex

► $0 + 2i$

► $1 + 0i$

► $2 + 7i$

$$i^2 = -1$$

$$(3+2i)*(1+1i) = 3+5i+2i^2 = 1+5i$$

The Formula

$$\boxed{z_{i+1} = z_i^2 + c} \quad (1)$$

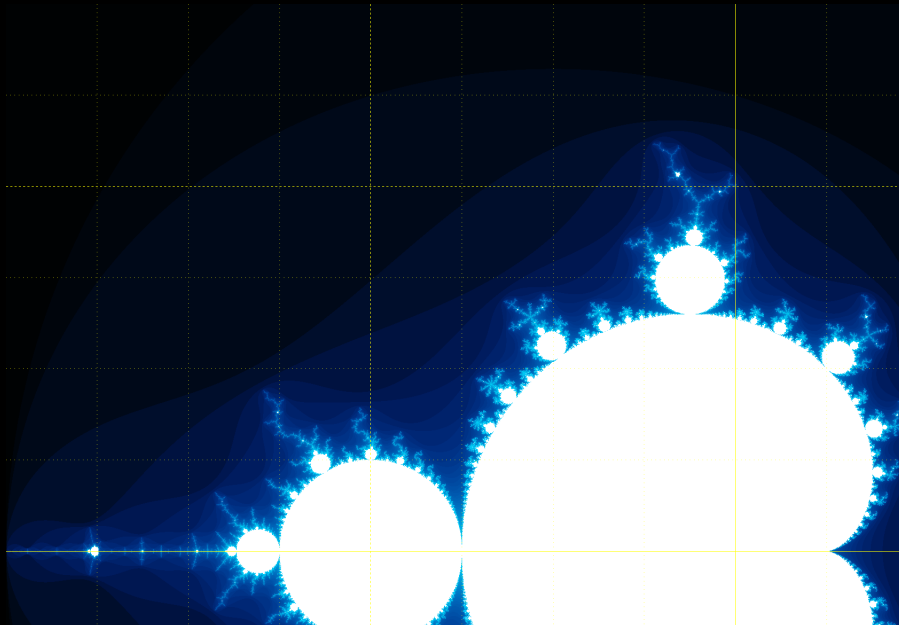
where

- ▶ $z_0 := 0 + 0i$
- ▶ $c := x + yi$

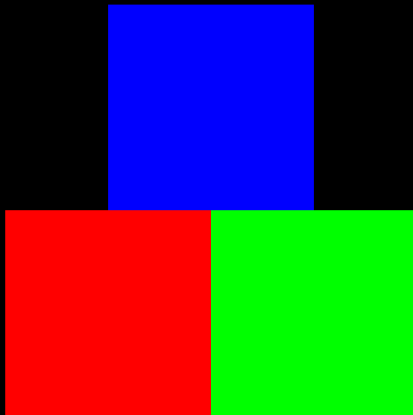
for every pixel:

- ▶ $z \rightarrow 0 \Rightarrow z \in M$
- ▶ $z \rightarrow \infty \Rightarrow z \notin M$

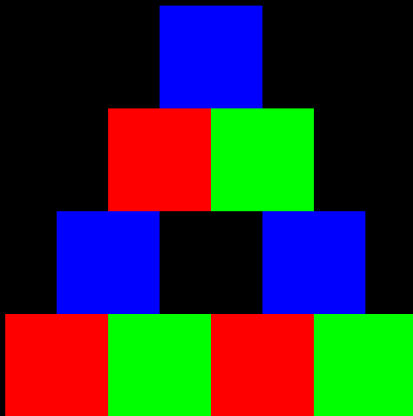
with color



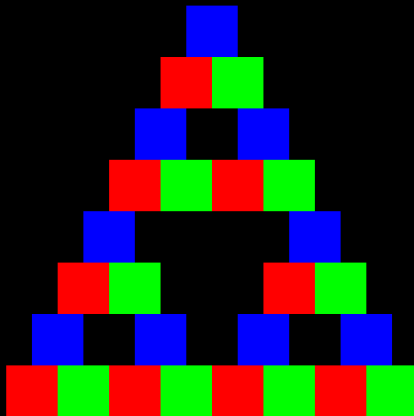
Iterated Function System



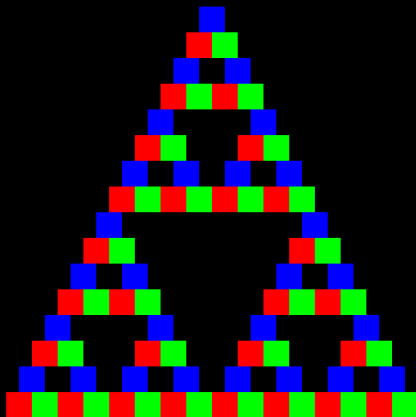
Iterated Function System



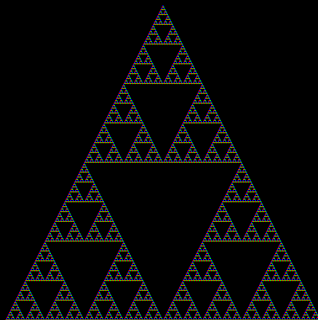
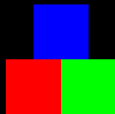
Iterated Function System



Iterated Function System



Iterated Function System

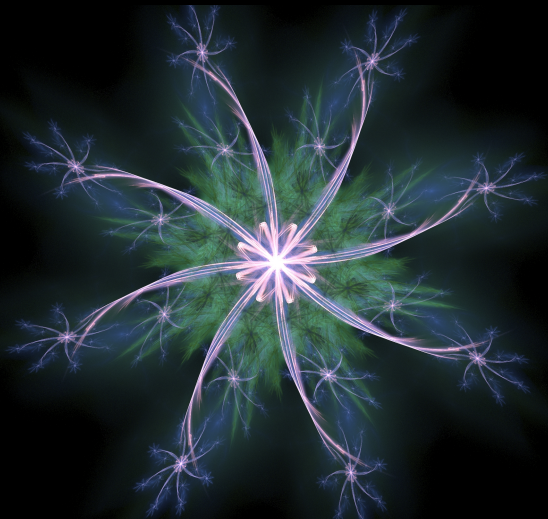


another IFS



“Fractal Flames”

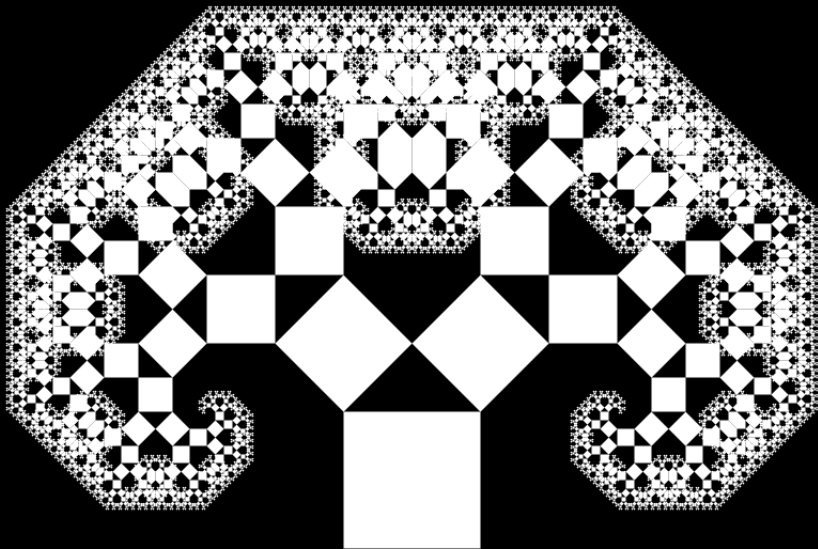




Nature



Nature



Nature



Nature



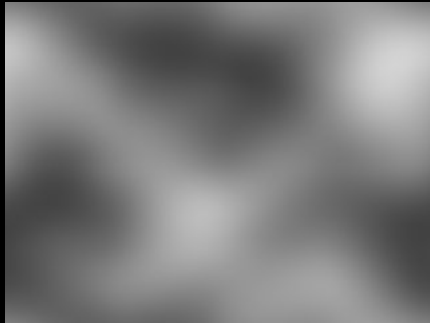
Pause?

Fractal Noise

We want a pattern that

- ▶ is “random”
- ▶ contains structure of various sizes
- ▶ looks “natural”

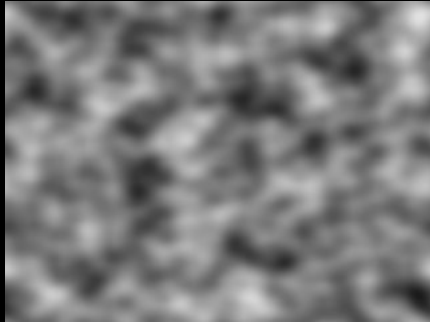
blurred Noise



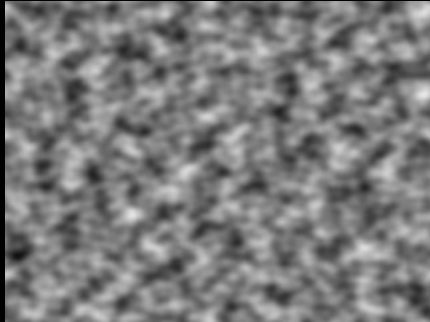
Next octave



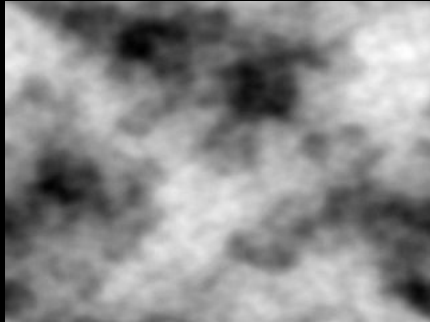
Next octave



Next octave



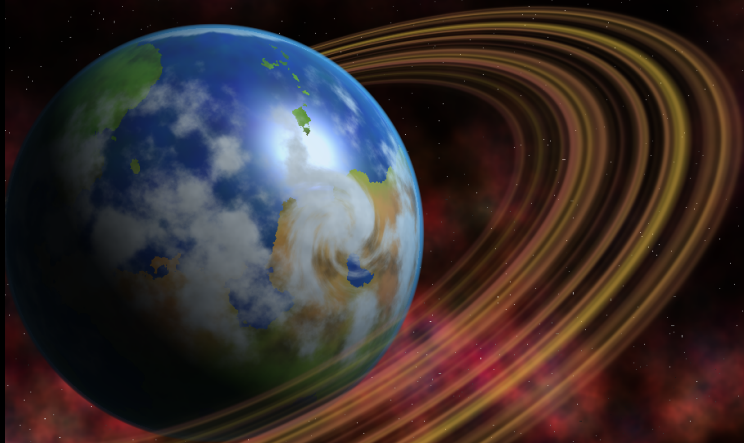
Summing four octaves



This is called “Perlin Noise” and everybody uses it.

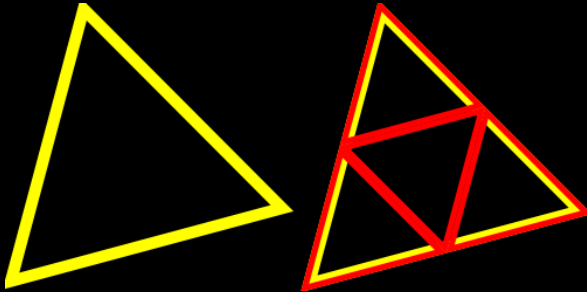
Usage

- ▶ clouds
- ▶ height fields (terrain)
- ▶ wood, marble
- ▶ can be animated by using more dimensions



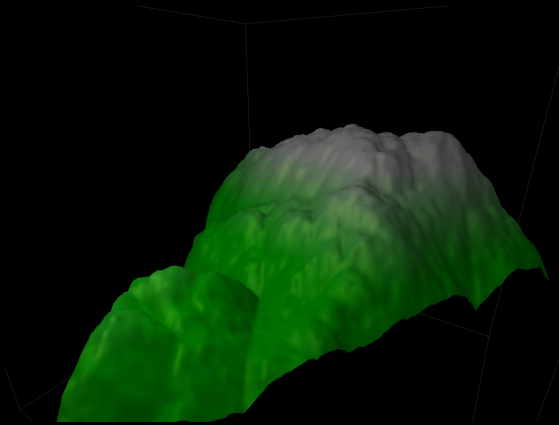
More Terrain

Take a mesh of triangles and repeat:

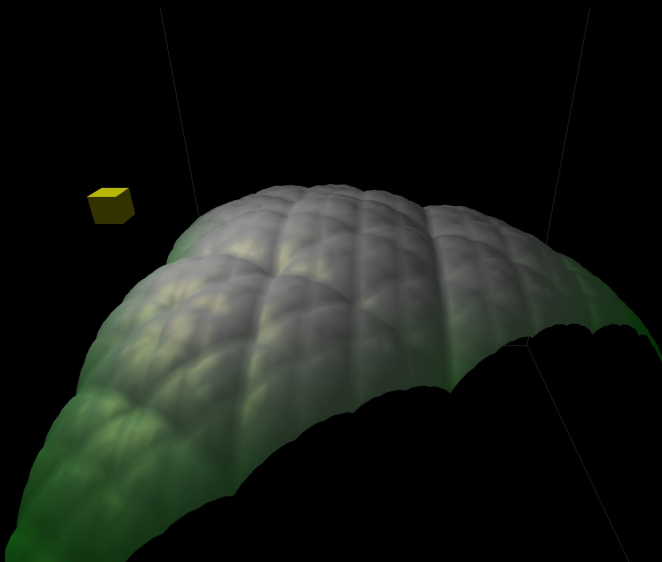


- ▶ subdivide by cutting the edges at their midpoints
- ▶ displace the midpoints

Midpoint Displacement



sucks, because



Rendering

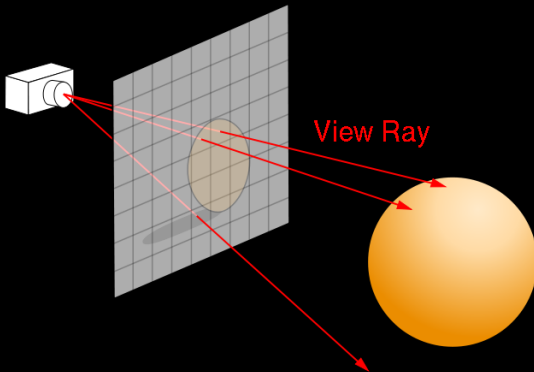
input:

- ▶ Geometry
- ▶ Material

output:

- ▶ pixels

Rendering



Geometry Representation

- ▶ Geometric Primitives
- ▶ Voxels, Point Clouds
- ▶ Polygons
- ▶ Isosurfaces

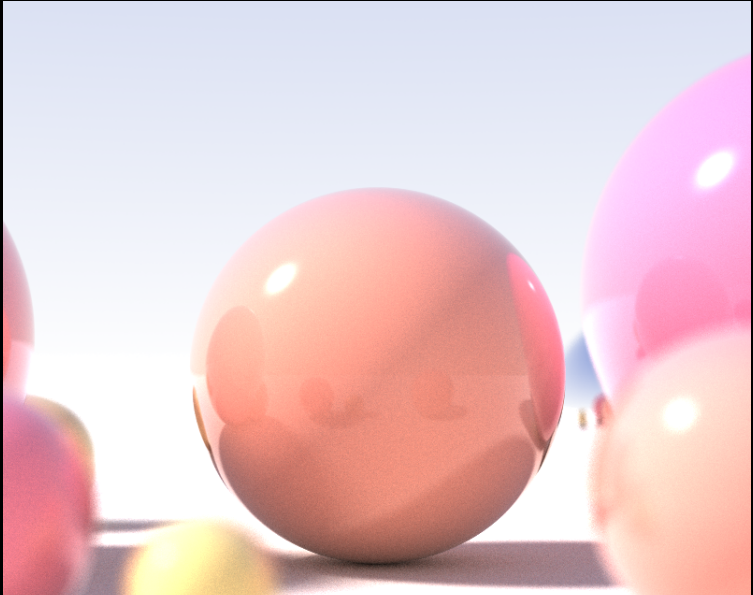
Geometric Primitives

Spheres, Cubes, Cylinders, ...

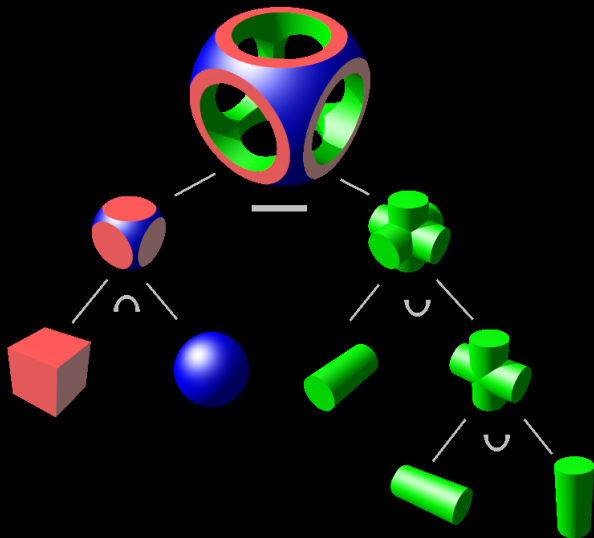
- ▶ Sphere stored as center, radius
- ▶ Store transformations, boolean operations

(Constructive Solid Geometry)

Geometric Primitives



CSG

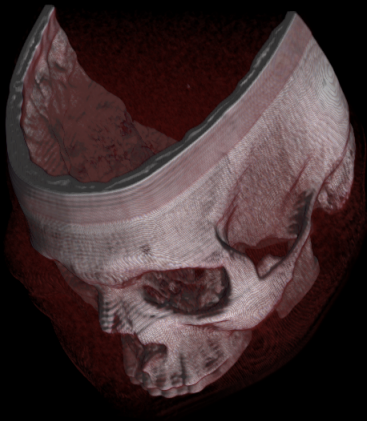


Voxels

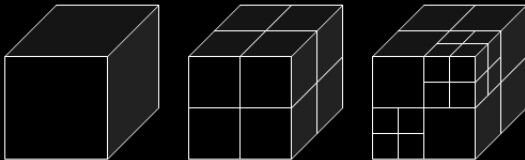
- ▶ Divide 3D space into equally sized voxels
- ▶ Store one bit per voxel

Used in medical imaging, old (and maybe future) games, movies

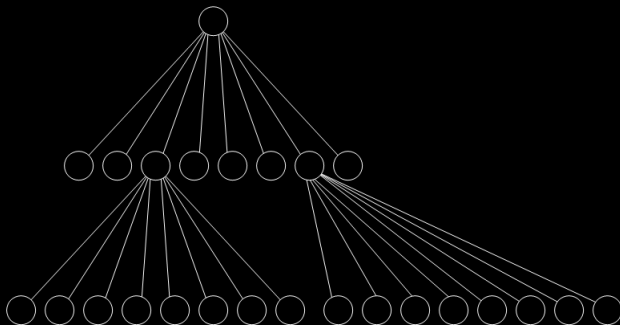
Voxels



Octree



Octree



Polygons

- ▶ Store points and connectivity
- ▶ Provides no concept of “inside” and “outside”

Used in games, movies

Polygons



Polygons

- ▶ generally unsorted (“polygon soup”)
- ▶ need to be triangulated for rendering \rightsquigarrow triangles.

Isosurfaces

- ▶ $f : \mathbb{R}^3 \rightarrow \mathbb{R}$
- ▶ visualize the surface where that function yields some constant value c :
$$f(\vec{x}) = c$$

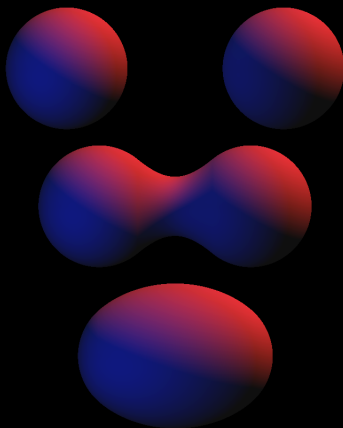
Example

f is the sum of the “distances”
between \vec{x} and two given points \vec{a}
and \vec{b} :

$$f(\vec{x}) = myDist(\vec{x}, \vec{a}) + myDist(\vec{x}, \vec{b})$$

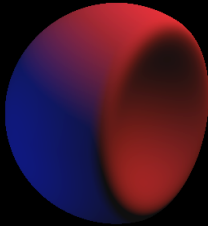
Example

$$f(\vec{x}) = \text{myDist}(\vec{x}, \vec{a}) + \text{myDist}(\vec{x}, \vec{b})$$



Example

$$f(\vec{x}) = \textit{myDist}(\vec{x}, \vec{a}) - \textit{myDist}(\vec{x}, \vec{b})$$



Rendering Isosurfaces

two possibilities:

- ▶ walk view rays while evaluating f , approximate intersection
- ▶ transform into a lots of polygons

Isosurface



Appearance

- ▶ lighting
- ▶ material

Illumination

- ▶ local
- ▶ global

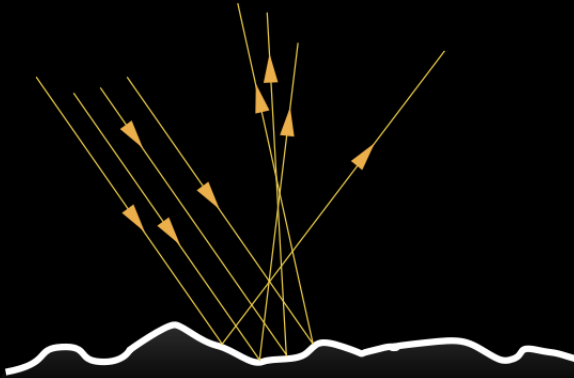
Material

“Material” models

- ▶ micro-geometry
- ▶ color
- ▶ light transmission

Micro-Scale

micro-scale roughness: matte surface



Diffuse Reflection



Real Image



Lambertian Model



Oren-Nayar Model

Meso-Scale

meso-scale roughness: small visible bumps



Macro-Scale

macro-scale roughness: we have
geometry for that

Color

usually stored in one or more textures

Appearance

can vary according to

- ▶ light color
- ▶ light angle, viewing angle
(velvet)
- ▶ environment (mirror, glass)

~> there can be no comprehensive
model

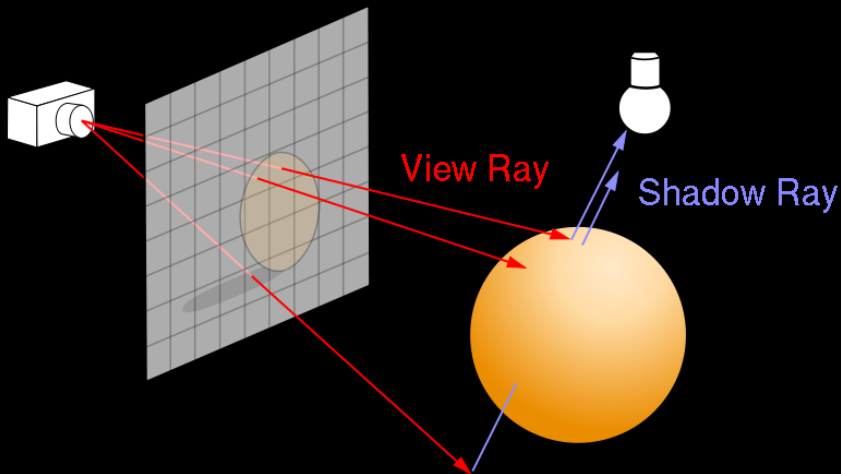
Offline Rendering

- ▶ static scene, no user interaction
- ▶ no hard time constraints

Realtime Rendering

- ▶ time constraint: 20msec
- ▶ a whole industry built around clever cheating

Ray Tracing



Ray Tracing



Tracing “photons” from the light source is also possible

Rasterization

for each object:

- ▶ project it onto the viewing plane
- ▶ paint all the pixels it covers

Painter's Algorithm

- ▶ sort objects
- ▶ draw from back to front

Sucks

- ▶ wasteful in scenes with high occlusion
- ▶ can't handle intersections
- ▶ sorting is in $O(n \log n)$

Z-Buffer Algorithm

- ▶ draw objects in any order
- ▶ for every pixel, store distance to camera in a buffer
- ▶ paint pixel only if distance to camera is lower

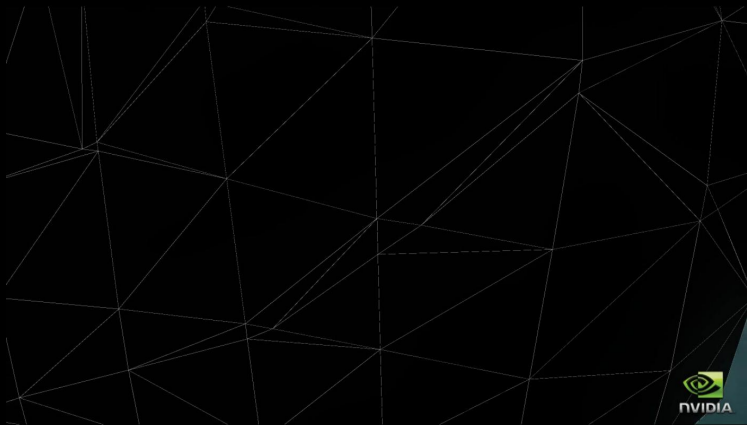
Next time

- ▶ graphics pipeline and hardware
- ▶ wicked techniques
- ▶ GPGPU, future technologies
- ▶ demos



CRIS DONNER AND HENRIK HØRN JENSEN - RENDERED USING DALI - 2006

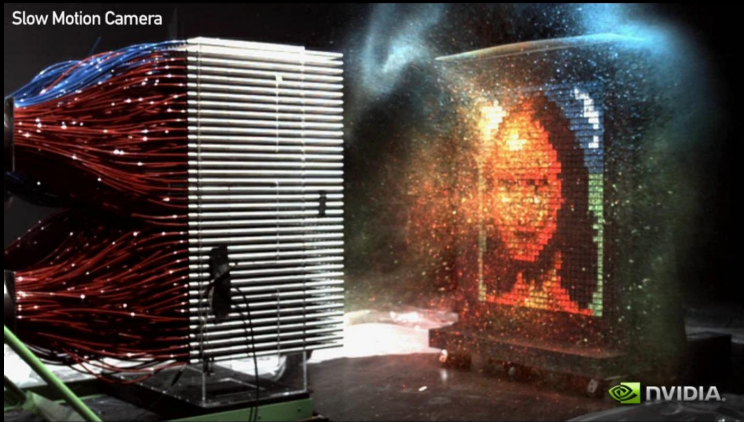






500 GFLOPS vs. 10 GFLOPS

Slow Motion Camera



Questions?

This work is hereby published under the Creative Commons Attribution License. It is also published under the GNU FDL and LGPL. Since i am not able to release anything into the public domain in germany, i hereby grant you all other imaginable rights to do with it as you wish. (this does not apply to the works of others reproduced here, of course)

For a list of the images used in the slides and attribution information, see the file part1-license.txt that is included in the archive that you downloaded.

If you feel that your copyright has been violated, please contact me.

Johann 'cupe' Korndorfer